

Author: Hongtao Wang  
 Advisor: Rubén Ruiz; Eva Vallada; María Fulgencia Villa  
 Ph.D Program in Statistic and Operational Research



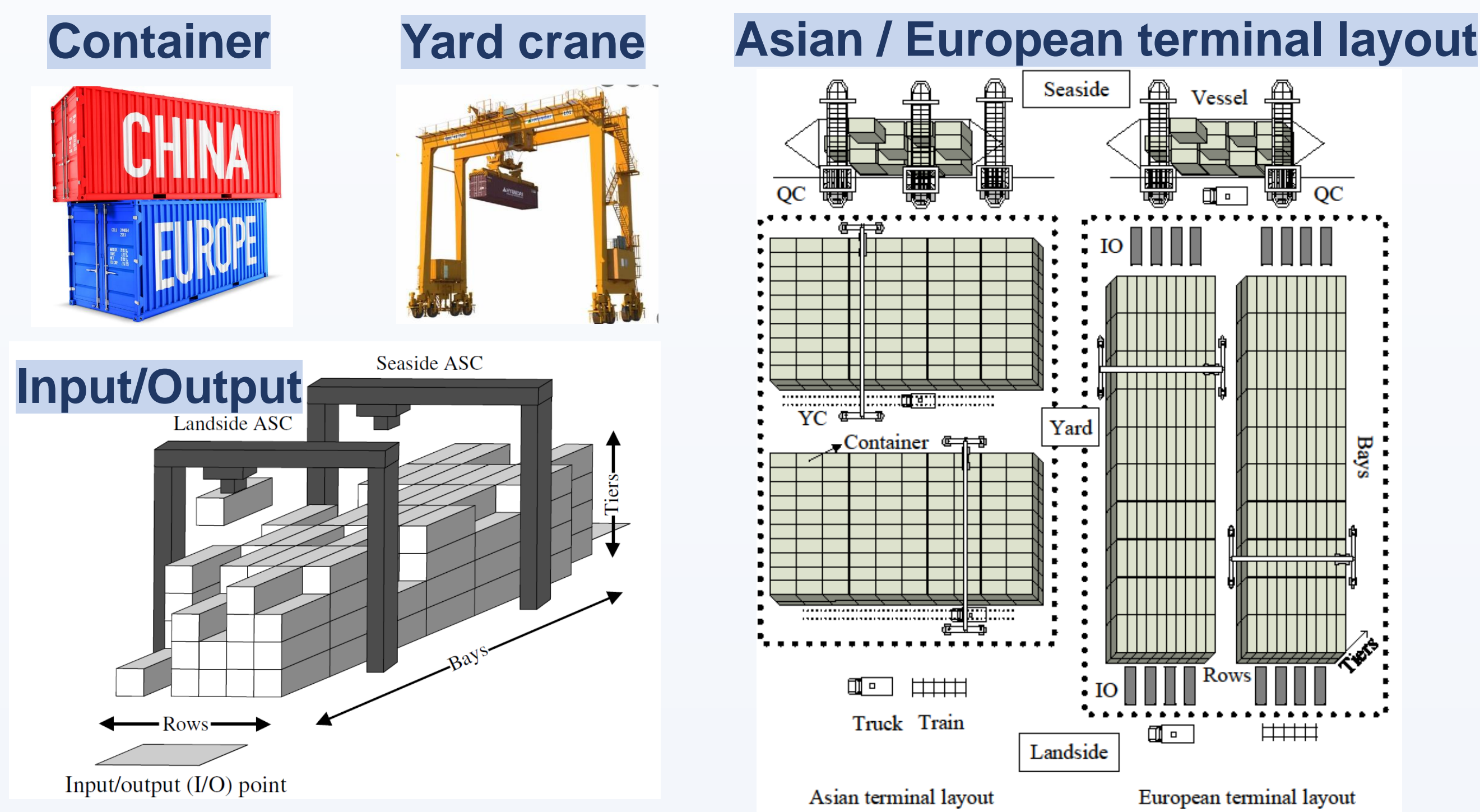
## 1-Abstract

This poster introduces a combined metaheuristic, Iterated Greedy (IG) method for the single yard crane scheduling problem with input/output points (IO) assignment.

- In the scheduling problem we consider the occupancy of IOs with the release time or due date of the container among which the caused tardiness/earliness and congestion are penalized.
- For the complexities of the problem, we introduce a series of constructive and heuristic methods for both container sequencing and IO assignment. The methods are assembled as well as calibrated IG and GRASP structure coupled with local search and IO heuristics.

## 2-Background

- we consider a European terminal configuration which is also popular for the full automatic terminals.
- In the terminal, all the containers are delivered between yard and two sides by one yard crane over the block.
- Every time the crane can transport only one container without break or temporary stop in our assumptions and it must be delivered by one IO in each side.
- We presume that most of the containers are already placed on the top of each stack, and for containers located on the middle which need to be reshuffled, the reshuffling times are considered as the constants.



## 3- Mathematical Model

- The problem is actually a **yard crane scheduling problem** with **IO assignment** in which a list of jobs are sequenced with assigned IOs to minimize the total **weighted tardiness and congestion**.
- In the terminal, due to the arriving time of the container, AGVs or trucks, the containers are delivered with the release times. Ideally, the job are expected to be finished on the time, beyond which the container may be late for the vessels or trucks resulting in **tardiness**.
- The crane may not able to load the containers on time, making the congestion when all the IOs are occupied by the containers waiting to be loaded. In the operational level, the tardiness and congestion should be penalized. Therefore, minimizing the weighted tardiness and **congestion** is the objective of the terminal

$$\min \sum_{c \in C} w_c^t (F_c - t_c) + \sum_{c \in C_1 \cup C_2} w_c^c (SO_c - t_c) + \sum_{c \in C_3} w_c^c E_c$$

$$\text{s.t.} \quad \sum_{k \in K} \sum_{j \in C_k} X_{ckj} = 1 \quad \forall c \in C$$

$$\sum_{c \in C} \sum_{j \in C_k} X_{ckj} = 1 \quad \forall k \in K$$

$$SO_c \leq SL_c \quad \forall c \in C_1 \cup C_2$$

$$F_c = EL_c \quad \forall c \in C_1 \cup C_2$$

$$SO_c = EL_c \quad \forall c \in C_3 \cup C_4$$

$$F_c \geq SO_c \quad \forall c \in C_3 \cup C_4$$

$$SO_c \geq t_c \quad \forall c \in C \setminus C_3$$

$$E_c = t_c - SO_c + T_c \quad \forall c \in C_3$$

$$F_c \geq t_c \quad \forall c \in C$$

Loading - Constraints(12) - (19).

- Obj: Minimize the lateness, congestion.
- TSP- like (Traveling salesman problem) model
- Variable time definition constraints
- Loading constraints of variables

## 4-Iterated Greedy for GRASP

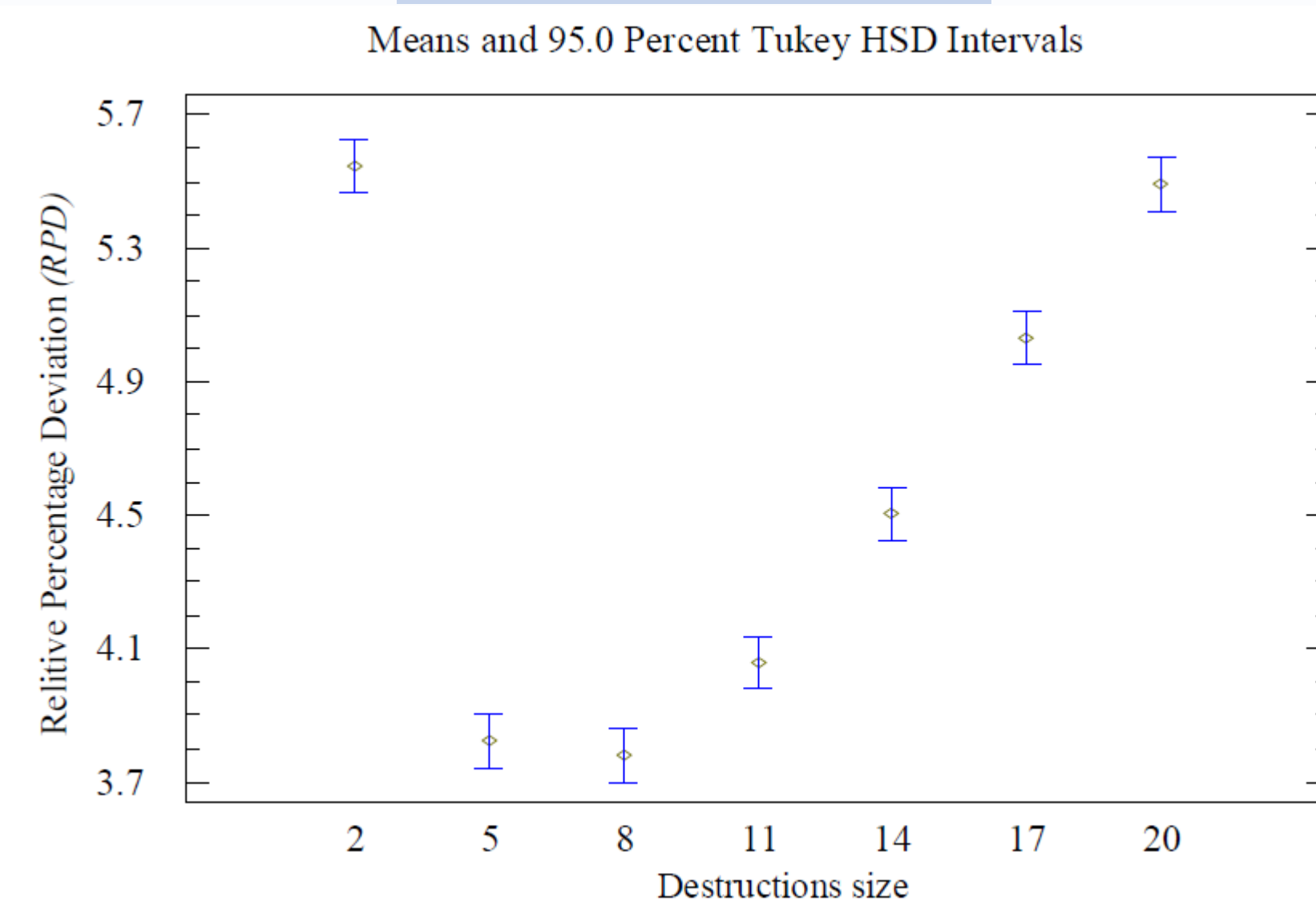
- Step 1: start with a Initial sequence
- Step 2: Solution destruction and reconstruction
- Step 3: Local search to improving the solution quality
- Step 4: IO heuristic for better IO assignment
- Step 5: Solution selection by the acceptance criteria

### Main operators of the IG

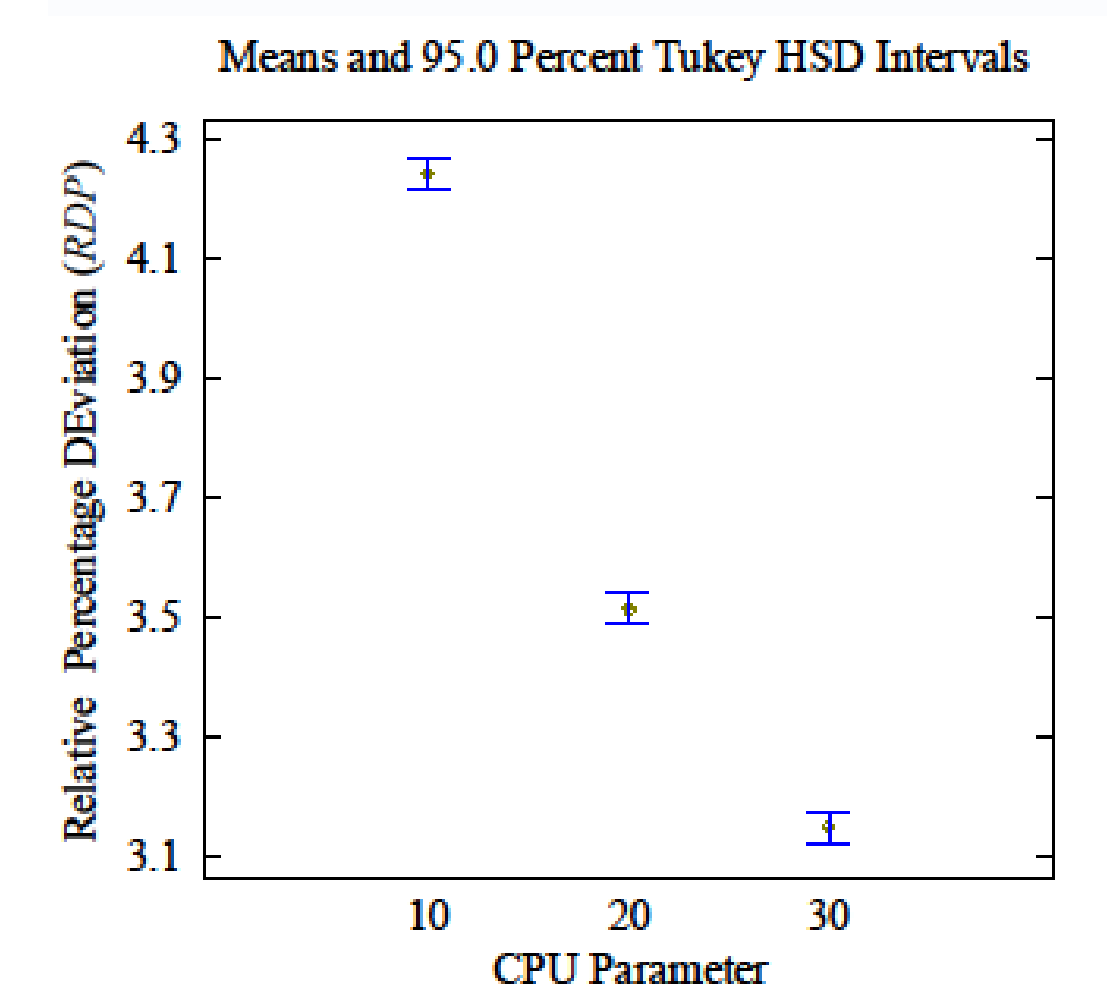
```
Algorithm : Iterated Greedy (IG)
1:  $\pi_0 :=$  Generated Initial TRP/MTRP/NCR Solution ;
2:  $\pi :=$  Local Search( $\pi_0$ );
3: while termination criteria is not satisfied do
4:   improvement := True;
5:    $\pi_1 :=$  Destruction( $\pi$ );
6:    $\pi_2 :=$  Reconstruction( $\pi_1$ );
7:    $\pi_3 :=$  Local Search( $\pi_2$ ),  $\pi_2 < \pi$ ;
8:    $\pi_4 :=$  IO Heuristic( $\pi_3$ );
9:    $\pi :=$  Acceptance Criterion( $\pi_4$ );
10: end while
```

## 5-Calibration of the parameters

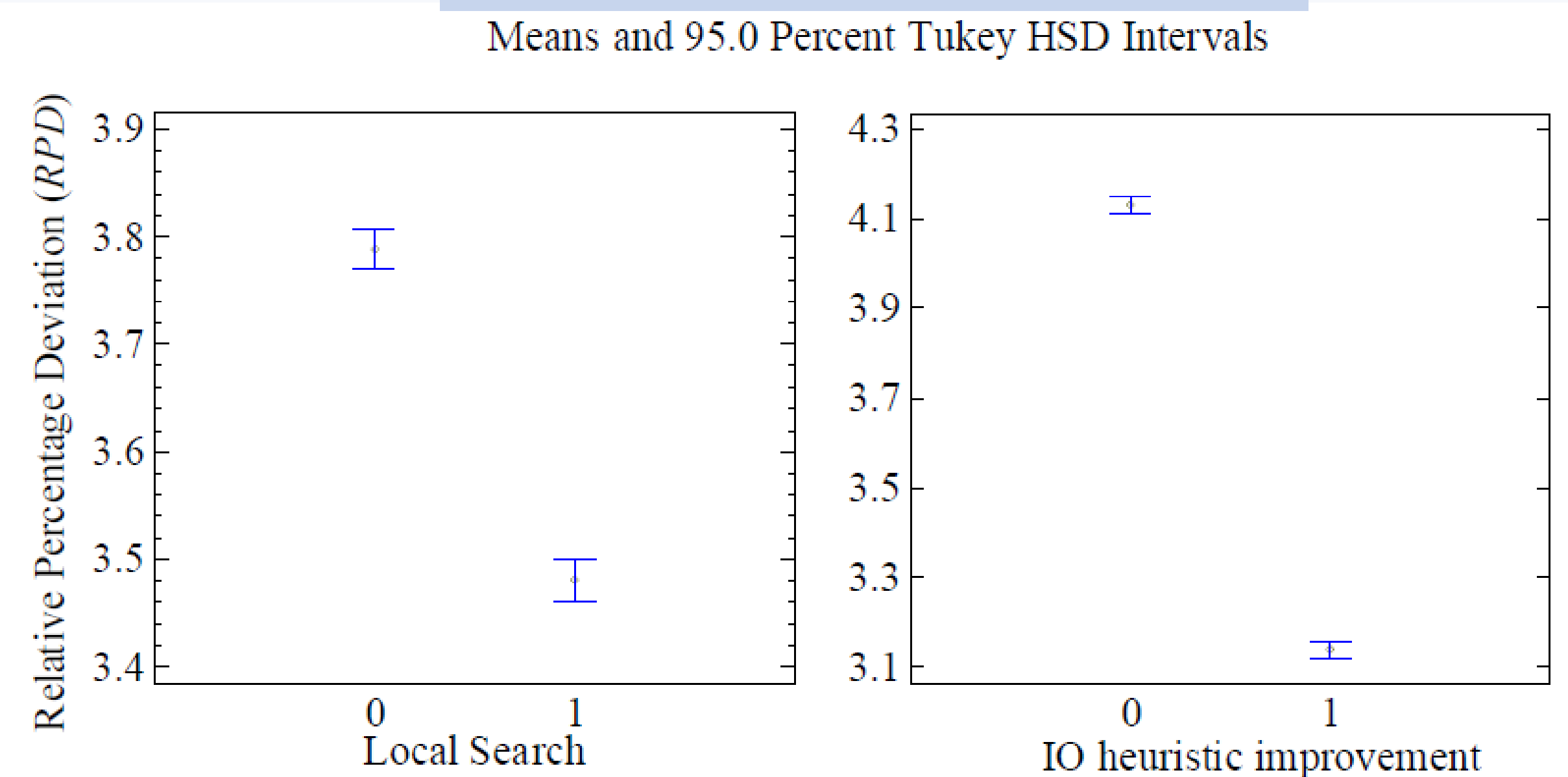
### Destruction size



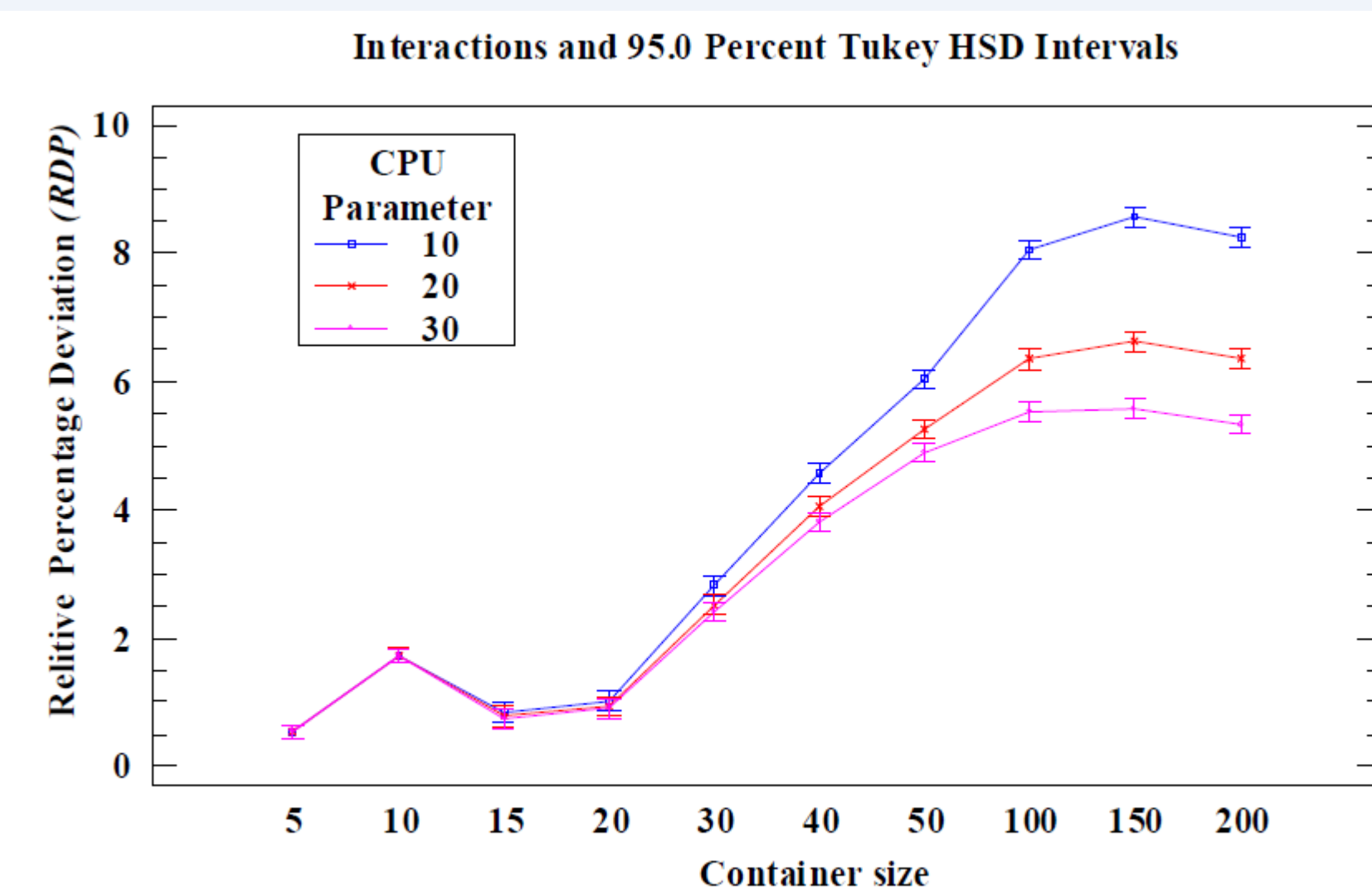
### Cpu-time Parameter



### Local search and IO heuristic



## 6-Performance of the method



### Brief summary:

- Relative percentage deviation (RPD) =  $\frac{Current_s - Best_s}{Best_s} * 100\%$
- Operators are significant in ANOVA
- More CPU time, lower RPD
- All RPDs are very small (<10%)

## Appendix-Extension application: Valencia Port

